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# Object concepts and action: Extracting affordances from objects parts

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## Abstract

Two experiments with a part-generation task show that rated salience and production order of parts in artifacts are first predicted by their relevance for canonical actions, but also that they vary, depending on the current situation.

In three further experiments participants read sentences describing actions (e.g., ‘The woman shares the orange’) followed by objects’ parts from which it was easy or not to extract affordances (e.g., ‘slice’ vs. ‘pulp’). They had to perform a part verification task or to evaluate whether or not the combination made sense. Parts from which it was easy to derive affordances were processed earlier and the combination was evaluated as the one which made more sense.

Overall, results support the view that sensory-motor simulations underlie conceptualization and that concepts are action-based.

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## 1. Introduction

### 1.1. General framework

Amodal views of conceptual knowledge assume that concepts, i.e., our knowledge units about categories, are represented through propositional symbols. The relationship between these symbols and their referents is arbitrary. Amodal views are usually

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26 based on the premise that perceptual and motor experience is translated into amodal  
27 and abstract symbols (Fodor, 1975; Smith & Medin, 1981; for a recent powerful for-  
28 mulation of this view see Landauer & Dumais, 1997). So, for example, the concept  
29 ‘cup’ would be represented through propositional features such as ‘has a handle,’  
30 ‘you drink from it,’ and so on. There is no relationship between the features we asso-  
31 ciate with the cup and the sensory-motor experience we have when we see a cup or  
32 drink from it.

33 A logical consequence of this vision of concepts is the assumption that the seman-  
34 tic system, where knowledge is “contained”, is clearly differentiated from the other  
35 modular systems of perception and action (Rumiati & Humphreys, 1998; Tulving,  
36 1972).

37 As far as research programs are concerned, the adoption of amodal views of con-  
38 ceptual knowledge has often led researchers to focus on the stable rather than on the  
39 flexible aspects of conceptual organization (see for example the critiques of Smith,  
40 1995). This does not mean that symbolic amodal theories cannot account for or pre-  
41 dict variability in conceptual organization (Landauer & Dumais, 1997). Simply, the  
42 source of this variability is ascribed to semantic relatedness between concepts and to  
43 frequency and is not attributed to the re-enactment of a sensory-motor experience.

44 Recently, in different fields, a different view of the relationship between cognition,  
45 perception and action has begun to gain credit (Thelen & Smith, 1994). In particular,  
46 it has been proposed that cognition is embodied, i.e., that it depends on the kind of  
47 experiences produced as a result of our having a body with a particular sensory-mo-  
48 tor system. This view of cognition is clearly in opposition with the classical cognitivist  
49 view, according to which the mind is a device for manipulating arbitrary symbols.  
50 In line with this perspective, the view held by Gibson (1979) has been given new res-  
51 onance. Many theories in various fields, from those regarding perception to those  
52 regarding attention, to language (Berthoz, 1997; Humphreys & Riddoch, 2001; Li-  
53 berman & Whalen, 2000; Rizzolatti & Arbib, 1998; Rizzolatti, Riggio, Dascola, &  
54 Umiltà, 1987), share the idea that perception, action and cognitive systems cannot  
55 be considered as separated, and defend the claim that cognition is deeply grounded  
56 in sensory-motor processes. For example, in the field of vision studies, O’Regan and  
57 Noë (2001) have recently proposed that seeing is a way of acting, i.e., that it is a way  
58 of exploring the environment. Accordingly, the experience of seeing occurs when the  
59 organism masters the governing laws of sensorimotor contingency.

60 In the field of categorization, as well, a different view of conceptual knowledge has  
61 begun to gain credit in recent years. It has been argued that the existence of a trans-  
62 lation process—from sensory experience into amodal symbols—is not necessary, nor  
63 is it plausible from an evolutionary point of view. In this perspective, concepts are  
64 conceived of as re-enhancement of neural activation patterns, directly referring to  
65 sensory-motor experiences (Barsalou, 1999; Barsalou, Simmons, Barbey, & Wilson,  
66 2003).

67 Much neural evidence convergent with this view has been provided: in particular,  
68 proponents of the sensory-motor theory, on the basis of functional neuroimaging  
69 data, argue that conceptual knowledge does not constitute information which is  
70 physically distinct from modality specific input and output representation. On the

71 contrary, “the features that define an object are stored close to the primary sensory  
72 and motor areas that were active when information about that object was acquired”  
73 (Martin, Ungerleider, & Haxby, 2001, p. 1023; for a review adopting a different po-  
74 sition, see Mahon & Caramazza, in press).

75 An implication of this view is that, because knowledge is anchored in experience,  
76 it cannot be separated from perception and action. In antithesis with the amodal  
77 view, recent studies show that perception, action and cognition are deeply related.  
78 This idea was anticipated by Gibson’s (1979) theory, according to which perception  
79 is not a channel of information flow made of different processing stages (Sternberg,  
80 1969) but it is deeply influenced by action and movement. Much neurophysiological  
81 evidence is consistent with the view of the reciprocal interaction of action intention  
82 and perceptual systems (Jeannerod, Arbib, Rizzolatti, & Sakata, 1995; Knoblich &  
83 Flach, 2001; Prinz, 1997; Ward, 1999). On the behavioral side, recent evidence indi-  
84 cates that the relationships between perception and action may be reciprocal. Tucker  
85 and Ellis (1998, 2001) have shown that the vision of an object may directly elicit ac-  
86 tion patterns independent of the intentions of the subject: for example, the vision of a  
87 cup elicits (affords) the action of grasping it, and the vision of objects different in size  
88 elicits different kinds of grasping (precision vs. power grasp). Bekkering and Neggers  
89 (2002) have shown that the intention to perform an action modulates visual process-  
90 ing by favoring the perceptual features that are related to action. They measured the  
91 accuracy of saccades in grasping and pointing to target objects that could have a dif-  
92 ferent orientation (45° vs. 135°) and color (green vs. orange). They found that the  
93 first eye movement was more accurate in selecting a target object with a given orien-  
94 tation located in the midst of distractors when the object had to be grasped after-  
95 wards than when it had to be pointed to. There was no difference in errors  
96 between conditions when participants had to select an object with a predetermined  
97 color. Given that orientation is relevant for grasping but not for pointing, the results  
98 indicate that action planning influences visual processing. The fact that action inten-  
99 tion (e.g., grasp vs. point) leads to different ways of focusing on visual properties can  
100 deeply influence theories on concepts. In this line, recent proposals argue that con-  
101 ceptualization has its basis in both perception and action, and that it has the adap-  
102 tive role of preparing for situated action (Barsalou, 2002). Thus, concepts, i.e., our  
103 knowledge units, can be conceived of as the coding of possible interaction patterns  
104 with the world surrounding us (Glenberg, 1997).

105 A further implication of this view is that, because knowledge is grounded in bod-  
106 ily and situational experience, conceptual variability is highly stressed. In fact,  
107 depending on our kind of body and on the situation we are experiencing, different  
108 conceptual aspects are activated. Accordingly, concepts are conceived of as situated  
109 and embodied, because they vary depending on the situation and on the relations be-  
110 tween their referents and our body (Barsalou, 1987, 1999; Smith & Samuelson,  
111 1997).

112 A central notion for the view that “knowledge is for action” (Wilson, 2002) is that  
113 of affordance (Gibson, 1979), for two reasons: (1) because it demonstrates the close  
114 connection between perception and action, and (2) because it provides an under-  
115 standing of the importance of variability and situationatedness. Affordances are

116 ways in which a perceiver can interact with an object. Thus the notion of affordance  
117 is not an absolute one. Depending on the constraints of our body, on the perceptual  
118 characteristics of objects and on the situation at hand, different objects or different  
119 parts of objects may afford actions. When we are driving a car, its steering wheel  
120 may become particularly salient for guiding our actions, while when we are repairing  
121 a car, its motor may become more salient. However, regardless of the current situa-  
122 tion, both the car's steering wheel and motor are probably more salient for the con-  
123 cept 'car' than other parts typically less salient for acting, such as the roof.

## 124 1.2. *Aim and hypotheses*

125 If the claim that "knowledge is for action" is true, an important function of con-  
126 cepts may reside in the role they play when one is preparing for situated actions  
127 (Barsalou, 2002). The advantage of preserving perceptual and motor characteristics  
128 of conceptual referents may reside in facilitating our interaction with objects.

129 The aim of this paper is to verify whether objects are represented as patterns of  
130 potential actions by focusing on their parts. But what is a part? Different proposals  
131 have been advanced, in order to define parts. For example, Biederman (1987) pro-  
132 posed that it is possible to segment objects into a set of 3-D volumetric primitives  
133 called geons. In a different view, Hoffman and Richards (1984) have proposed that  
134 individuals are more likely to identify a particular patch of shape as a part because  
135 it lies between two points of extreme negative curvatures, rather than assuming that  
136 objects are parsed into primitive shapes. Here, parts are defined in a very broad  
137 sense, as any fragment or component of an object-stimulus. Given that the studies  
138 proposed involve three tasks which imply a linguistic mediation—a part production,  
139 a part verification and a sensibility-evaluation on parts task—parts with an easily  
140 expressible name will have an advantage over components of objects without a  
141 name.

142 Parts are particularly important because actions are generally directed towards  
143 them. There is much evidence showing that objects are represented componentially  
144 (Biederman, 1987), and that parts play a special role for object concepts, especially  
145 for basic level ones (Murphy, 1991; Rakinson & Butterworth, 1998; Schyns & Mur-  
146 phy, 1994; Tversky, 1989; Tversky & Hemenway, 1984). In particular, as the action  
147 intention selects perceptually relevant properties in perception, in conceptualization  
148 different parts should also be activated depending on the activated action and situ-  
149 ation.

150 If concepts are not represented as patterns of potential actions,

- 1a. the salience of a part should be independent of the role parts play for guiding acting;
- 1b. the salience of a part should not vary depending on the currently activated ac-  
tion.

155 If object concepts are represented as embodied and situated entities (Barsalou,  
156 1999; Pecher, Zeelenberg, & Barsalou, 2003),

- 2a. the salience of a part should depend on the role parts play for canonical actions directed towards an object, i.e., the most important parts in an object concept should be the ones affording the more frequent actions performed with it;
- 2b. the salience of a part should vary depending on the currently activated action.

161 Hypotheses 2a and 2b are not conflicting; in fact, it is plausible that not all possible  
162 affordances are necessarily activated during a simulation, only affordances elicited by  
163 canonical actions as well as affordances relevant for the current goals (Kaschak &  
164 Glenberg, 2000; Zwaan, Stanfield, & Yaxley, 2002). The term “simulation” refers  
165 to the fact that we may simulate an object, for example a car, in its absence (Barsalou,  
166 1999), because we have integrated the properties of the object in a coherent and orga-  
167 nized system. Thus we might simulate cars’ parts by re-enhancing the sensory-motor  
168 experience we have had with them. The same is true for event sequences. For example,  
169 the simulation of the event sequence of moving a table focuses on the actions involved  
170 in lifting and pushing it, but not on the experience of eating on it.

### 171 1.3. Overview of the present experiments

172 To test these hypotheses in Experiments 1 and 2 a feature generation task was used,  
173 which is widely assumed to assess the way concepts are represented (Tversky & He-  
174 menway, 1984; Wu & Barsalou, submitted for publication).

175 Consider that modal views naturally predict that concepts, similarly to percepts,  
176 have perspectives, i.e., that activated features are best predicted by action and the cur-  
177 rent context. It would be reductive, however, to argue that amodal theories cannot ex-  
178 plain these effects. Proponents of such theories might account for such results by  
179 arguing, for example, that certain concept parts have stronger semantic associations  
180 with certain situations than with others.

181 In particular, proponents of the amodal view might claim that feature production  
182 tasks are not sufficiently informative, as their results might be explained by the fact  
183 that there are simply stronger lexical associations, say, among words denoting parts  
184 within a given perspective than across different perspectives. For this reason in Exper-  
185 iments 3 and 4 a part verification task was used, and in Experiment 5 a sensibility-rat-  
186 ing task of words and sentences was used. These methods allow an easier control of  
187 the association degree between words denoting parts and words and sentences denot-  
188 ing situations, and make it possible to rule out the hypotheses that the results might be  
189 due to semantic associations rather than to the creation of mental simulations of the  
190 objects.

191 Experiment 3 tests with a part verification task the hypothesis that different parts  
192 are activated depending on the action expressed by a sentence. If it is true that process-  
193 ing a sentence like ‘He grasped the knife’ activates a mental simulation of the scene,  
194 and if it is true that objects are represented componentially (Biederman, 1987), the  
195 part ‘handle’ following the sentence should be verified faster than the part ‘blade’,  
196 due to the fact that the part ‘handle’ better affords the action of grasping a knife than  
197 the part ‘blade’. Consider, however, a possible objection to this experiment. The dem-  
198 onstration that different actions activate different parts may simply show that concep-

199 tual organization is variable, but not that concepts are represented through simula-  
200 tions preserving their perceptual and motor characteristics. Simply, such a result  
201 could be explained by a semantic network account: the verb 'grasp' may be more  
202 semantically associated with 'handle' than with 'blade', while the verb 'cut' may be  
203 more semantically associated with 'blade' than with 'handle'.

204 In order to rule out a semantic network account, in Experiments 4 and 5 parts were  
205 selected which were not semantically associated to a given action, but which, due to  
206 their perceptual features, might or might not afford a particular action (see Glenberg  
207 & Robertson, 2000). Parts from which it is easy to extract affordances will be called  
208 affording parts. For example, the neck of a bottle can more easily afford the action of  
209 putting it down than its cork, even though neither the word 'neck' nor the word 'cork'  
210 are strongly semantically associated with the sentence expressing the action of putting  
211 something down. Experiment 4 tests whether affording parts are processed quicker  
212 than non-affording parts in a part verification task; Experiment 5 tests whether afford-  
213 ing parts are considered more sensible in the context of sentences compared with non-  
214 affording parts. If affording parts are processed earlier and evaluated as being more  
215 plausible than non-affording parts, this advantage cannot be due to the semantic  
216 relatedness between words denoting parts and sentences. Thus, the results will favor  
217 the view according to which concepts are simulations preserving perceptual and mo-  
218 tor characteristics of objects. A possible advantage of preserving perceptual charac-  
219 teristics of objects is to prepare for situated action (Glenberg, 1997), thus  
220 facilitating interaction with the object.

## 221 2. Experiment 1

222 In this experiment the type of simulated interaction with objects was manipulated:  
223 three groups of participants were required to imagine using/acting, building, or seeing  
224 objects. For the critical objects they were also required to produce parts. If hypothesis  
225 1 is true, i.e., if concepts are represented through amodal and arbitrary symbols and  
226 are stable across situations, then (a) parts relevant for acting should not be produced  
227 more frequently across conditions and earlier than other parts; (b) the same parts  
228 should be generated in the three situations and in the same production order. If  
229 hypothesis 2 is true, i.e., if concepts are represented as patterns of potential actions  
230 in terms of perceptual symbols, then (a) parts relevant for canonical actions should  
231 be produced across all situations and should be produced earlier than other parts;  
232 (b) in the building and vision situation there should be an interaction: parts more rel-  
233 evant for building should be produced more frequently and earlier in the building  
234 than in the vision situation; the opposite should be true for the vision situation.

### 235 2.1. Participants

236 Forty-eight students of the University of Bologna, native Italian speakers between  
237 the ages of 19 and 24, volunteered for the experiment. Sixteen participants were ran-  
238 domly assigned to each of the three groups between participants conditions.

239 2.2. *Material*

240 Twenty-eight concept names were selected, 14 of which referred to objects that  
241 could be used/acted upon, built or seen, 14 of which referred to objects or entities  
242 that could not (e.g., phantom, alien). Special care was taken in selecting the seven  
243 critical concept-nouns among the 14 concepts referring to objects which could be  
244 used/acted upon, built or seen: bicycle, car, hi-fi, mixer, motorbike, piano, and wash-  
245 ing machine. A pilot study was run in which six independent participants evaluated a  
246 list of 15 complex artifacts concept-nouns, chosen because they have parts differently  
247 relevant in the three situations of acting/using, building and seeing the objects. Note  
248 that the Italian words used contain no cues as to possible parts or actions, as their  
249 English counterparts do. The seven critical concept-nouns were the concepts which,  
250 according to all raters, were characterized by the fact that they have parts which are  
251 differentially relevant for each of the three situations. In fact, all of the selected arti-  
252 facts, regardless of their size and complexity, are characterized by having three dif-  
253 ferent kinds of parts. They all have external parts, often protruding from the object's  
254 main structure, which typically afford actions: for example the car's steering wheel,  
255 the handle of a bicycle and of a bike and the keys and buttons of the washing ma-  
256 chine, the hi-fi and the mixer. They also have external parts, which do not protrude  
257 from the object's main structure but often constitute it. These objects are typically  
258 larger than the first ones but typically do not elicit goal-directed actions, as for exam-  
259 ple the car's roof and sides, the structure of the hi-fi, the tail of the piano. Finally, all  
260 the selected artifacts have internal parts which determine the way the objects work  
261 but are not perceptible from the outside and are not relevant for canonical action  
262 with the object, even though they are very important for building the objects, as  
263 for example the motor of the car, the chain of the bicycle, the wires of the hi-fi.

264 2.3. *Procedure*

265 The paradigm used was very similar to that developed in Borghi and Barsalou  
266 (2001). Participants, who were individually interviewed, had to perform an imagery  
267 decision task, i.e., they were asked whether they could imagine themselves or some-  
268 body else either using, building or seeing an object, depending on the experimental  
269 condition. Participants could answer 'yes' or 'no' to the question, which was repeated  
270 for each concept. Immediately after having answered 'yes' or 'no' for the seven crit-  
271 ical concepts they were also asked to produce the parts of the objects they referred  
272 to. The part-generation task was embedded within an imagery decision task in order  
273 to avoid rendering the task transparent.

274 2.4. *Transcription and rating*

275 The tape-recorded interviews were transcribed. For each participant both the  
276 parts produced and the sequential position in which each part was produced (first,  
277 etc.) were reported.

278 Four independent raters were asked to evaluate on a seven-point scale the impor-  
279 tance of each part produced for acting/using, building and seeing each object. Each  
280 rater saw the produced parts in a different random order and did not know in which  
281 situation (action/use, building or vision) they had been produced.

## 282 2.5. Results

### 283 2.5.1. Frequency

284 The frequency of the parts produced in the action/use situation ( $M = 3.71$ ) was  
285 lower than that of the parts produced in the build ( $M = 4.89$ ; Newman–Keuls  
286  $p < 0.03$ ) and vision situations ( $M = 4.95$ ; Newman–Keuls  $p < 0.05$ )  
287 ( $F(2, 45) = 3.61$ ,  $MSe = 2.15$ ,  $p > 0.05$ ).

### 288 2.5.2. Rated perspective

289 The scaled ratings were applied to the individual protocols in order to see  
290 whether, for a given protocol, the parts produced reflected one perspective more than  
291 the other and whether the parts reflecting a given perspective were produced first.

292 2.5.2.1. *Parts dominant in one perspective.* The parts whose average rating in one  
293 perspective was at least one point higher than the max of the average ratings of the  
294 two other perspectives were selected. For each concept there was a sub-group of  
295 parts dominant in each perspective. For example, for the concept ‘car,’ ‘accelerator’  
296 and ‘pedals’ were dominant in the action/use perspective, ‘transmission’ in the build  
297 perspective, and ‘windshield’ in the vision perspective.

298 2.5.2.2. *Ratings.* The average rating of each part for each perspective (act/use, build  
299 and vision) was multiplied by the frequency of the produced parts (0, 1) for each  
300 participant. Consider that in studies on categorization with feature generation tasks  
301 the features produced are typically coded according to a norm—for example, the  
302 features produced for a given concept are distinguished according to thematic  
303 properties, taxonomic properties, attributive properties etc. (Borghi & Caramelli,  
304 2003; Lin & Murphy, 2001). This presupposes that the same relation cannot be at the  
305 same time both thematic and taxonomic, or that the percentage of overlap is not  
306 high. Typically, two people code the properties produced according to a norm (for  
307 examples, see Barsalou, Solomon, & Wu, 1999), and the frequency of the coded  
308 properties are treated with statistical analysis. In this study it would be difficult and  
309 simplistic to code each part as relevant only for one situation—building, action/use,  
310 vision. For this reason, four coders, instead of two, were asked to rate the impor-  
311 tance of each part for each perspective using a seven-point scale (instead of a yes or  
312 no coding). This made it possible to obtain a weighted coding instead of a dichot-  
313 omic coding (e.g., to consider each property as linked exclusively with vision, action,  
314 or building). On the frequency of the coded parts an ANOVA was performed.

315 The design was mixed in the ANOVA, because Situation (action/use, build and  
316 vision) was manipulated between participants and Ratings within participants.  
317 The two main effects of Situation ( $F(2, 45) = 5.70$ ,  $MSe = 0.11$ ,  $p < 0.01$ ) and Rat-



ings ( $F(2, 90) = 63.51$ ,  $MSe = 0.049$ ,  $p < 0.01$ ) were significant, as well as the interaction ( $F(12, 90) = 13.44$ ,  $MSe = 0.049$ ,  $p < 0.01$ ). Overall, across situations the parts produced were those which were rated higher according to the action/use perspective than both the build and vision perspectives (Newman-Keuls,  $p < 0.01$ ). This indicates that the canonical perspective activated for objects is the action/use one. However, the interaction indicates that in the build Situation participants produced mainly parts relevant to building, while in the vision Situation they produced parts relevant to vision (Newman-Keuls,  $p < 0.01$ ). This shows that object parts are differently activated depending on the perspective with which they are accessed (see Fig. 1).

2.5.2.3. *Ratings  $\times$  Position.* The average rating on each part for each perspective (action/use, building and vision) was multiplied by the position of the produced part by each participant according to the following formula:  $(n + 1 - p)/(n - 1)^*r$ , where  $n$  is the total number of parts produced by each participant for each concept,  $p$  the position in which each part was produced and  $r$  the average rating on that particular

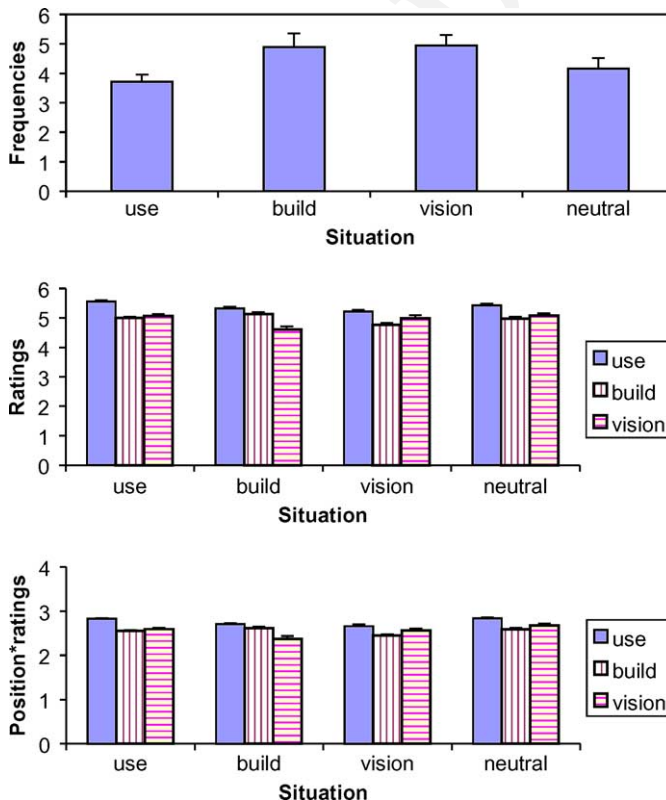


Fig. 1. Experiments 1 and 2. Frequency and rated Perspective by Frequency and by Position of the produced parts in each Situation.

333 part (for a similar procedure, see Wu & Barsalou, submitted for publication). This  
334 normalized  $p$ , the position in which each part was produced, in relation to  $n$ , the total  
335 number of parts produced by each participant, so that, for example, the first position  
336 within a total of 10 properties was considered as more relevant than the first position  
337 within a total of two properties.

338 Overall, across the three situations the parts relevant for action/use were produced  
339 earlier than those produced in both the building and vision situations (Newman–Ke-  
340 uls,  $p < 0.01$ ). The interaction between building and vision indicates that the parts  
341 produced earlier in the building Situation are parts relevant for building, in the vi-  
342 sion Situation are parts relevant for vision (Newman–Keuls,  $p < 0.01$ ). In the ANO-  
343 VA the two main effects of Situation ( $F(2, 45) = 7.22$ ,  $MSe = 0.02$ ,  $p < 0.01$ ),  
344 Ratings  $\times$  Position ( $F(2, 90) = 36.43$ ,  $MSe = 0.02$ ,  $p < 0.01$ ), and the interaction  
345 ( $F(4, 90) = 8.36$ ,  $MSe = 0.02$ ,  $p < 0.01$ ) were significant. The results obtained con-  
346 firm that object concepts are conceived in terms of their affordances, i.e., of the parts  
347 which elicit actions, but they also demonstrate that depending on the situation, dif-  
348 ferent parts are activated.

### 349 2.6. Discussion

350 The results support the predictions of the embodied and situated view of concepts.  
351 In fact, parts produced more frequently and earlier across situations are those rated  
352 as relevant for canonical actions, i.e., for using the object (hypothesis 2a). In addi-  
353 tion, depending on the kind of simulated interaction with objects (building vs. vi-  
354 sion), different parts become salient for concepts (hypothesis 2b). Thus  
355 conceptualization is both body and situation dependent.

## 356 3. Experiment 2

357 If object concepts are represented as action-based, then in a neutral condition the  
358 parts relevant for actions should be those which are rated as most important and  
359 produced earlier. Experiment 2 represents a control experiment of Experiment 1,  
360 consisting of a simple part-generation task, performed without asking participants  
361 to simulate a particular situation.

### 362 3.1. Participants

363 Sixteen students of the University of Bologna, native Italian speakers, volunteered  
364 for the experiment.

### 365 3.2. Material

366 The same seven critical trials used in Experiment 1 were used in this experiment.

367 3.3. Procedure

368 The procedure differed from that of Experiment 1 only in that participants, who  
369 were individually interviewed, did not perform the imagery decision task but only the  
370 part-generation task.

371 3.4. Transcription

372 As in Experiment 1 the interviews were transcribed and for each participant both  
373 the parts produced and the position in which they were produced were recorded.

374 3.5. Results

375 3.5.1. Rated perspective

376 The scaled ratings of Experiment 1 were applied to the individual protocols of  
377 Experiment 2 in order to see whether, for a given protocol, the parts produced re-  
378 flected one perspective more than the other, and whether the parts reflecting a given  
379 perspective were produced first.

380 3.5.1.1. Ratings. As in Experiment 1, the average rating on each part for each per-  
381 spective (action/use, building and vision) collected in Experiment 1 was multiplied by  
382 the frequency of the produced parts (0, 1) by each participant in this Experiment.

383 In order to see whether the parts produced in the neutral Situation reflected one  
384 perspective more than the others, an ANOVA was performed with the variable Rat-  
385 ings at three levels (action/use, building and vision), manipulated within participants.  
386 The parts produced were those which were rated higher according to the action/use  
387 perspective than both the building and vision perspectives ( $F(2, 30) = 31.81$ ,  
388  $MSe = 0.027$ ,  $p < 0.01$ ) (Newman–Keuls,  $p < 0.01$ ). This confirms the trend found  
389 in Experiment 1.

390 3.5.1.2. Ratings  $\times$  Position. The average rating on each part for each perspective  
391 (action/use, building and vision) was multiplied for the position of the produced part  
392 by each participant following the same formula used in Experiment 1. The results of  
393 the ANOVA show that the parts produced earlier are those which obtained higher  
394 ratings in the action/use perspective than in both the building and vision perspectives  
395 ( $F(2, 30) = 21.56$ ,  $MSe = 0.01$ ,  $p < 0.01$ ) (Newman–Keuls,  $p < 0.01$ ).

396 3.6. Discussion

397 The results of Experiment 2 show that when participants are not asked to simulate  
398 objects in a specific situation the saliency of object parts depends on their role for  
399 action (hypothesis 2a). In order to better disentangle the results, the data of Exper-  
400 iments 1 and 2 were compared directly.

#### 401 4. Comparison between Experiments 1 and 2

402 If hypothesis 2a is true, i.e., object concepts are patterns of potential actions and  
403 the canonical perspective in which objects are represented is action/use dependent,  
404 then the results obtained in Experiment 2, i.e., in a part-generation task performed  
405 in a neutral condition, should resemble those obtained in the action/use condition of  
406 Experiment 1 and differ from those obtained in the building and vision situations of  
407 Experiment 1 (see Fig. 1).

#### 408 4.1. Results

##### 409 4.1.1. Frequency

410 The frequency of the parts produced in the four situations (E1 action/use, E1  
411 building, E1 vision, E2 neutral) was compared. The average frequency of the parts  
412 produced in E2 was higher than that of parts produced in E1 action/use situation,  
413 but much lower than that produced in the E1 building and E1 vision Situation  
414 ( $F(3, 60) = 2.70$ ,  $MSe = 2.10$ ,  $p < 0.05$ ). Post hoc Newman–Keuls showed that the  
415 E1 action/use situation differs from both the E1 building ( $p < 0.2$ ) and the E1 vision  
416 situations ( $p < 0.03$ ). The E2 neutral situation does not differ significantly from any  
417 of the other situations.

##### 418 4.1.2. Rated perspective

419 4.1.2.1. Ratings. An ANOVA was performed with the variables Situation at four  
420 levels (E1 action/use, E1 building, E1 vision, E2 neutral) and Ratings at three levels  
421 (action/use, building, vision). Both the E1 action/use and the E2 neutral situations  
422 had the same pattern of results differing from the other two situations. The two main  
423 effects of both Situation ( $F(3, 60) = 4.17$ ,  $MSe = 0.126$ ,  $p < 0.01$ ) and Ratings  
424 ( $F(2, 120) = 89.20$ ,  $MSe = 0.04$ ,  $p < 0.01$ ) were significant as well as the interaction  
425 ( $F(12, 120) = 10.798$ ,  $MSe = 0.04$ ,  $p < 0.01$ ). Post hoc Newman–Keuls shows that  
426 the E1 action/use and the E2 neutral situations do not differ but both differ from the  
427 other two situations (Newman–Keuls,  $p < 0.01$ ).

428 4.1.2.2. Ratings  $\times$  Position. The same result was found in the ANOVA on positions.  
429 The effects of Situation ( $F(2, 60) = 9.65$ ,  $MSe = 0.02$ ,  $p < 0.01$ ), Ratings  $\times$  Position  
430 ( $F(2, 120) = 52.57$ ,  $MSe = 0.02$ ,  $p < 0.01$ ) and the interaction ( $F(6, 120) = 6.99$ ,  
431  $MSe = 0.017$ ,  $p < 0.01$ ) reached significance. Again, the E1 action/use and the E2  
432 neutral situations differed from both the E1 building and the E1 vision ones  
433 (Newman–Keuls,  $p < 0.01$ ).

#### 434 4.2. Discussion

435 Hypothesis 2a is confirmed. In fact, across the four situations the parts relevant  
436 for action/use were produced earlier than those produced in both the building and  
437 vision situations. In addition, the pattern of data obtained in the neutral situation  
438 strongly resembles that of the action/use situation.

439 It can be argued that the parts of artifact concepts which are activated in a neutral  
440 condition, and those which are activated earlier, are not those which are more visible  
441 or more important structurally, but those which are more relevant for acting with  
442 objects.

443 Consider, however, a possible objection to the previous experiments. A proponent  
444 of the amodal view might claim that a feature production task is not sufficiently  
445 informative, as the results of the first two experiments might also be explained by  
446 stronger lexical associations among words denoting parts within a given perspective  
447 than among words across different perspectives.

448 It is possible to respond to this objection both theoretically and from a method-  
449 ological approach. From a theoretical point of view, it can be objected that lexical  
450 associations are grounded in and originated in perceptual and action experience.  
451 However, this argument might be considered too general.

452 Taking a closer look at the data, it can be said that Latent Semantic Analysis  
453 (LSA, Landauer & Dumais, 1997) would predict mostly situational effects, while  
454 the data show both canonical and situational effects. However, it can be argued that  
455 this is not completely true; in fact, the dominance of a situation across others might  
456 also be predicted by a word association account, without it being necessary to pos-  
457 tulate a perceptual simulation account.

458 In order to rule out possible objections, different methods were used: a faster part  
459 verification task and a sensibility-rating task made up of words and sentences. These  
460 methods have the advantage of making it easier to control for semantic associations  
461 between concept-nouns and sentences referring to situations.

462 Consider a further point. It might be argued that the results of Experiments 1 and  
463 2 hold only for complex artifact concepts, and more specifically for artifacts which  
464 can be manipulated and with which we generally perform actions, such as bicycles  
465 in comparison to statues. For this reason in Experiments 3–5 a further variable  
466 was introduced, the difference between concept kinds. Different studies, both behav-  
467 ioral and neural, show that artifacts elicit functional rather than perceptual attri-  
468 butes (Keil, 1989) and suggest that function and manipulation knowledge are  
469 critical for artifacts (Buxbaum, Schwartz, & Carew, 1997; Buxbaum, Sirigu, Sch-  
470 wartz, & Klatzky, 2003; Buxbaum, Veramonti, & Schwartz, 2000; Chaigneau &  
471 Barsalou, in press; Sirigu, Duhamel, & Poncet, 1991; for reviews see Borghi, submit-  
472 ted for publication; Capitani, Laiacona, Mahon, & Caramazza, 2003; Martin &  
473 Caramazza, 2003; Pulvermüller, 1999, 2003). Neuroimaging studies show that arti-  
474 facts activate pre-motor areas whereas living kinds activate brain regions involved  
475 in visual processing (Chao & Martin, 2000; Martin, Wiggs, Ungerleider, & Haxby,  
476 1996). Thus it can be hypothesized that artifacts' affording parts are more influenced  
477 by the selected action than natural kind affording parts.

### 478 5. Experiment 3

479 The aim of Experiment 3 is to show with a part verification task that, depending  
480 on the actions expressed by a sentence, different parts of an object are activated. For

481 example, the part ‘slice’, due to its perceptual features, better affords the action of  
482 dividing an orange than the part ‘pulp’.

483 Both artifacts and natural kind concepts were used in order to see whether the  
484 hypothesis according to which concepts are patterns of potential actions holds for  
485 both kinds of concepts or only for artifacts.

## 486 5.1. Method

### 487 5.1.1. Participants

488 Nineteen students of the University of Bologna were recruited for the experiment.  
489 A within-subjects design was used.

### 490 5.1.2. Material

491 The material consisted of 48 sentences of the form subject–verb–object (see  
492 Appendix A). Each sentence could be followed by two nouns indicating a part of  
493 the object, for a total of 96 trials. The object of half of the sentences was a basic level  
494 natural kind (e.g., flower), the object of the other half was a basic level artifact (e.g.,  
495 shirt). There could be either congruency between the action expressed in the sentence  
496 and the object part (‘the child divided the orange—slice’; ‘the child tasted the or-  
497 ange—pulp’) or not (‘the child divided the orange—pulp’; ‘the child tasted the or-  
498 ange—slice’). Each part was presented only in combination with one concept (e.g.,  
499 ‘slice’ was presented only in the two different sentences whose object was ‘orange’).  
500 The presented parts were controlled for length and familiarity. The same 96 sen-  
501 tences were presented followed by nouns that indicate parts, but not parts of the ob-  
502 ject mentioned in the sentence (e.g., ‘the child divided the orange—lever’), for a total  
503 of 192 sentences.

### 504 5.1.3. Procedure

505 The experiment started with 16 practice trials to familiarize the participants with  
506 the task. During each trial each participant first saw a horizontally centered fixation  
507 point; then a sentence appeared (e.g., ‘The girl read the book’); after 750 ms the sen-  
508 tence disappeared and a part noun appeared.

509 Participants had to press a button with their dominant hand as quickly as possible  
510 to indicate ‘yes, the noun is a part of the object of the sentence’ (e.g., ‘page’), and a  
511 button with their not dominant hand to indicate ‘no, it is not a part of the object of  
512 the sentence’ (e.g., ‘lever’). Participants were told to read the whole sentence and not  
513 just the object of the sentence.

## 514 5.2. Results

515 Analyses were conducted on both the RTs and the frequency of correct judge-  
516 ments. The analyses were performed only on the trials requiring a positive response.  
517 RTs were removed for target trials on which errors occurred. To reduce the effect of  
518 the outliers, RTs higher or lower than the average  $\pm 2$  standard deviations for each  
519 participant for each condition were eliminated, corresponding to 1.58% of the data.

520 The ANOVA on response times showed an effect of congruency of part and verb.  
 521 The difference in accuracy was also significant. Affording parts were processed faster  
 522 ( $M = 970$  ms instead of  $1076$  ms) ( $F(1, 18) = 5.38$ ,  $MSe = 39721.49$ ,  $p < 0.03$ ) and  
 523 elicited less errors ( $M = 1.82$  instead of  $M = 2.58$ ) than non-affording parts  
 524 ( $F(1, 18) = 10.12$ ,  $MSe = 1.09$ ,  $p < 0.01$ ). In the ANOVA on RTs the interaction be-  
 525 tween affordance and kind of concepts was also significant ( $F(1, 18) = 8.72$ ,  
 526  $MSe = 40000.31$ ,  $p < 0.01$ ); post hoc Newman–Keuls showed that this was due to  
 527 the fact that non-affording parts of artifacts were processed slower than affording  
 528 parts of artifacts and both affording and non-affording parts of natural kinds  
 529 ( $p < 0.01$ ) (see Fig. 2).

### 530 5.3. Discussion

531 The results indicate that different actions expressed by sentences activate different  
 532 object parts, i.e., that they activate the object parts which can be better combined  
 533 with the actions. Overall, affording parts, i.e., parts which are more congruent with  
 534 the action mentioned in the sentence (e.g., ‘the woman ate the watermelon—seeds’)  
 535 are processed faster and elicit less errors than non-affording parts (e.g., ‘the woman  
 536 ate the watermelon—skin’). The results support the argument that conceptual orga-  
 537 nization is variable, because concepts’ perceptual features are differentially accessed  
 538 depending on the activated action (Barsalou, 1987).

539 In addition, they show with a quick part verification task that object concepts are  
 540 activated componentially and not holistically (Biederman, 1987), because different  
 541 parts are activated depending on the action to perform on them.

542 Most interestingly, these results show that object concepts are represented as pat-  
 543 terns of potential actions. This is particularly true for artifact concepts. In fact, the  
 544 interaction between concept kinds and congruency between parts and actions shows

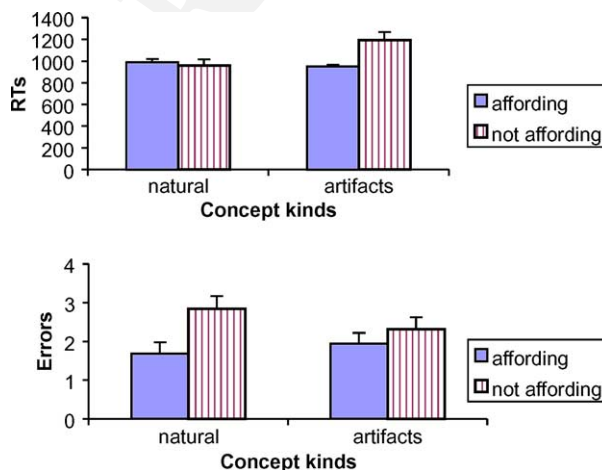


Fig. 2. Experiment 3. Differences in RTs and accuracy between affording and non-affording parts.

545 that in artifact concepts non-affording parts are processed slower than affording  
546 ones. Overall, the results reflect the deep relations between conceptualization, per-  
547 ception and action and support the perceptual symbols view of conceptualization.  
548 In fact, as occurs with perception, with conceptualization the action intention also  
549 selects relevant perceptual features.

550 However, an objection could be raised which invalidates the last point: given that  
551 the association degree between the verbs and the parts was not controlled, the results  
552 obtained do not completely rule out an account of concepts based on associations in  
553 a semantic network. In fact, the advantage of the pairs where there was congruency  
554 between action and part over those with no congruency may simply depend on the  
555 association degree between the verb and the object part (e.g., ‘divide’ could be more  
556 associated to ‘slice’ than to ‘pulp’), not on their being affordances for actions. The  
557 aim of Experiments 4 and 5 is to rule out this hypothesis by providing convergent  
558 evidence obtained with different tasks.

## 559 6. Experiment 4

560 The aim of Experiment 4 was to verify, using the same procedure, that the results  
561 of Experiment 3 were not simply due to word association but that they were the re-  
562 sult of a meshing process between the action to accomplish and the objects’ parts. A  
563 new list of trials was construed: the material was controlled so that in each sentence  
564 the verb was not more semantically associated to the affording than to the non-  
565 affording part.

### 566 6.1. Method

#### 567 6.1.1. Participants

568 Twenty-eight students of the University of Bologna volunteered their participa-  
569 tion. Both affordance (affording vs. non-affording parts) and concept kind (artifact  
570 vs. natural kind) were manipulated within participants.

#### 571 6.1.2. Material

572 The material consisted of 22 sentences, 11 of which had a natural kind concept as  
573 object and 11 of which had an artifact concept as object, followed either by a part  
574 which could be a good affordance for the expressed action or by a non-affording  
575 part, for a total of 44 trials. An example: ‘The child distributed the orange—slice’  
576 (natural kind, affording part); ‘The child distributed the orange—pulp’ (natural kind,  
577 non-affording part); ‘The boy lifted the wardrobe—legs’ (artifact, affording part);  
578 ‘The boy lifted the wardrobe—shutter’ (artifact, non-affording part). The material  
579 was selected after two pre-tests. In the first, 20 participants were asked to produce  
580 20 associates to the verb. None of the participants associated the critical parts to  
581 the verb. In the second pre-test, 20 participants were required to produce five asso-  
582 ciates to the whole sentence. Only a few associated parts were produced, and there  
583 was no difference in frequency and production order between affording and non-



584 affording parts. Part familiarity and length were controlled: there was no difference  
585 in familiarity of affording vs. non-affording parts ( $p < 0.188$ ) and the number of syl-  
586 lables of the parts was the same across the different conditions.

587 Forty-four fillers were added to the 44 trials in which the part following the sen-  
588 tence was not a part of the sentence's object (e.g., 'The child distributed the orange—  
589 nail').

### 590 6.1.3. Procedure

591 The procedure was the same as in Experiment 3: participants had to press a but-  
592 ton in order to decide whether or not the part noun following a sentence referred to a  
593 part of the sentence's object. They had to press the 'yes' button with their dominant  
594 hand. The trials were presented in a different random order for each participant. Six-  
595 teen practice trials preceded the experiment. Unlike Experiment 3, in this case par-  
596 ticipants were instructed to read the whole sentence preceding the part as they  
597 could be tested on it later. This slight modification was introduced in order to rule  
598 out the possibility that participants paid attention only to the object of the sentence  
599 and not to the whole sentence.

### 600 6.2. Results

601 The results of one participant were discarded because he/she had very slow RTs  
602 on some trials, indicating that he/she did not perform the task attentively enough.  
603 RTs were removed for target trials in which errors occurred. RTs higher or lower  
604 than the average  $\pm 2$  standard deviations for each participant for each condition were  
605 eliminated. In this way less than 2% of the data was eliminated. Overall, RTs in this  
606 experiment are longer than those in Experiment 3. This might have to do with the  
607 change in instruction, because participants in this experiment were invited to pay  
608 attention to the whole sentence as they could be tested on it later.

609 In the ANOVA performed on RTs there was a main effect of affordances: as ex-  
610 pected affording parts had shorter latencies than non-affording parts ( $M = 1134$  vs.  
611  $M = 1201$ ) ( $F(1, 26) = 5.58$ ,  $MSe = 21489.41$ ,  $p < 0.02$ ) with both artifacts and nat-  
612 ural kind concepts. In the accuracy analysis there was no effect of affordances, but  
613 the error means had the same trend as the latency means, showing that no speed-  
614 accuracy tradeoff occurred. A main effect of concept kinds ( $F(1, 26) = 11.84$ ,  
615  $MSe = 11.84$ ,  $p < 0.01$ ) showed that natural kind concepts elicited more errors than  
616 artifacts ( $M = 1.55$  vs.  $M = 1.07$ ). Also, the interaction was significant  
617 ( $F(1, 26) = 11.46$ ,  $MSe = 0.83$ ,  $p < 0.01$ ), due to the fact that artifact concepts elicited  
618 much fewer errors with affording parts than with non-affording parts ( $p < 0.01$ ) and  
619 with both affording ( $p < 0.01$ ) and non-affording parts of natural kind concepts  
620 ( $p < 0.01$ ), as shown by post hoc Newman-Keuls (see Fig. 3).

### 621 6.3. Discussion

622 The results confirm and strengthen those obtained in Experiment 3. As predicted,  
623 latencies were shorter with affording than with non-affording parts. This indicates

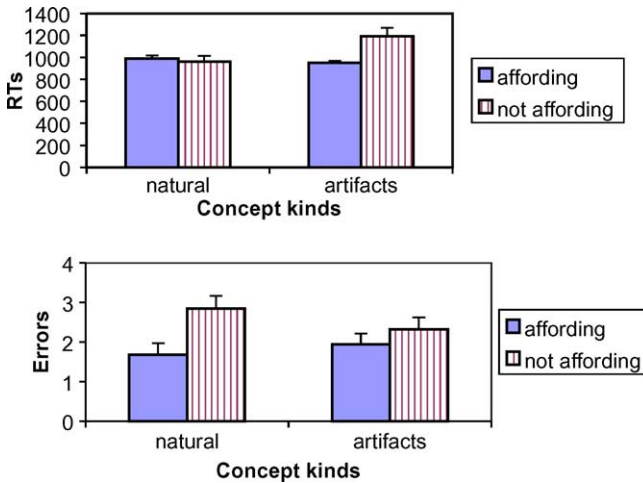


Fig. 3. Experiment 4. Differences in RTs and accuracy between affording and non-affording parts.

624 that not all affordances are automatically activated, but rather that only the affor-  
 625 dances that are activated by the sentence and relevant for its comprehension are acti-  
 626 vated automatically (Kaschak & Glenberg, 2000; Stanfield & Zwaan, 2001). In  
 627 addition, the results indicate that objects are not holistically represented but that dif-  
 628 ferent objects' parts can be affordances depending on the kind of action.

629 The accuracy analysis confirms what was found in Experiment 3: artifacts' parts  
 630 are stronger affordances than natural kinds' parts. This result is congruent with lit-  
 631 erature on the neural basis of cognition showing that while artifacts are processed  
 632 the sensory-motor cortex is activated.

## 633 7. Experiment 5

634 The aim of Experiment 5 is to confirm the results of Experiment 4 with a different  
 635 paradigm, i.e., to demonstrate that the results of Experiment 3 are not simply due to  
 636 word association but to the sentences expressing actions which selected affording  
 637 parts. The same material of Experiment 4 was used. The task consisted in rating  
 638 on a seven-point scale how much a given part made sense in combination with the  
 639 sentence.

640 The paradigm used strongly resembles the one used by Glenberg and Robertson  
 641 (2000) who found that participants evaluated as more sensible sentences like 'After  
 642 wading barefoot in the lake, Erik used his shirt to dry his feet' than sentences like  
 643 'After wading barefoot in the lake, Erik used his glasses to dry his feet'. The results  
 644 can be explained by the fact that shirts, due to their perceptual features, afford the  
 645 action of drying feet, whereas glasses do not.

## 646 7.1. Method

## 647 7.1.1. Participants

648 Twenty-one students of the University of Bologna volunteered for the experiment.  
649 Both affordance (affording vs. non-affording parts) and concept kind (artifact vs.  
650 natural kind) were manipulated within participants.

## 651 7.1.2. Material

652 The same material of Experiment 4 was used.

## 653 7.1.3. Procedure

654 Participants were presented with all the randomized trials and were asked to rate,  
655 using a seven-point scale, "How is the part following the sentence plausible in the  
656 context of the sentence?"

## 657 7.2. Results

658 Affording parts ( $M = 4.97$ ) were rated as more plausible in the sentence's context  
659 than non-affording parts ( $M = 3.47$ ) ( $F(1, 20) = 49.61$ ,  $MSe = 0.95$ ,  $p < 0.01$ ), de-  
660 spite the fact that the sentences and the parts were not associated (see Fig. 4).

## 661 7.3. Discussion

662 The results confirm and extend those obtained in Experiment 3.

663 First, they show the advantage of affording over non-affording parts with a differ-  
664 ent task, consisting of plausibility judgements. The difference between the affording  
665 and non-affording parts is not due to associations in a semantic network, given that  
666 both affording and non-affording parts are low associates of the preceding verb. It  
667 could be objected that this result is obvious, given that the parts used are certainly  
668 selected to be more plausible in a given context, and the ratings obtained are simply  
669 a consequence of the way the material was selected. Consider, however, the implica-  
670 tions of this result. Both kinds of sentences, those with affording and those with non-  
671 affording parts, are syntactically correct, and both are perfectly meaningful. Most  
672 importantly, the association degree between the verb of the sentence and the parts  
673 mentioned in the two sentences does not differ. This suggests that people make plau-

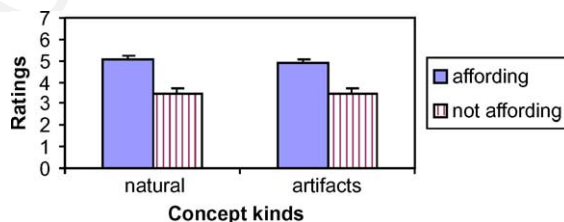


Fig. 4. Experiment 5. Differences in average sensibility-ratings between affording and non-affording parts.

674 sibility judgements by envisioning the perceptual characteristics of parts, extracting  
675 their affordances, and meshing them with the action expressed by the sentence (Glen-  
676 berg & Robertson, 2000). This process makes it possible to quickly understand the  
677 sentence's meaning. Indicating that parts with certain physical characteristics afford  
678 actions, the results suggest that objects and their parts are represented through per-  
679 ceptual symbols grounded in actions and not through arbitrary symbols. There is,  
680 however, a way in which amodal theories could explain such a result. It could be ar-  
681 gued that, while reading and evaluating sentences, one could come up with some line  
682 of reasoning to arrive at the interpretation that one part is more plausible than an-  
683 other in a given context. This is a plausible explanation. However, it is certainly less  
684 economical than the first—one should extract all the properties of a part and verify  
685 whether they match with the meaning conveyed by a given sentence. Further, this  
686 explanation would not fully clarify why participants evaluated a particular combina-  
687 tion as making sense quickly and easily.

688 A final point is worth noticing. The absence of a difference between artifacts and  
689 natural kinds opens the possibility that, for both kinds of concepts, parts afford ac-  
690 tions, i.e., that both artifacts and natural kinds can be conceived of as action-based  
691 concepts.

## 692 8. General discussion

693 The results have a number of theoretical implications.

694 First, they indicate that parts relevant for actions are activated more than other  
695 parts across situations; this suggests that objects are conceived of in terms of the po-  
696 tential actions we may perform with them (hypothesis 2a). The fact that default af-  
697 fordances are dictated by their importance for more frequent actions (Palmer,  
698 Rosch, & Chase, 1981) is very plausible from an evolutionary point of view. There  
699 is much evidence converging on the importance of default affordances: it is sufficient  
700 to think of the well known literature on functional-fixedness (Duncker, 1926), as well  
701 as of the more recent literature in cognitive ergonomics (Norman, 1988).

702 However, this is not the whole story. This research also shows that our cognitive  
703 system subserves action in a more subtle and sophisticated way, by storing informa-  
704 tion which might be relevant for future actions in different situations. In fact, the  
705 existence of default affordances does not exclude the variability of conceptual orga-  
706 nization; the results also indicate that, depending on the different kind of interaction  
707 with objects, different parts are affordances (hypothesis 2b). As in perception, in con-  
708 ceptualization the action intention also selects perceptual features apt for acting.  
709 Experiment 1 provides evidence supporting the view that different concept parts  
710 are activated depending on the simulated kind of interaction we have with objects:  
711 different parts are activated and with a different production order when we simulate  
712 to build objects or to visually interact with them. Experiment 3 shows, with a part  
713 verification task, that with the same object the parts activated (affordances) depend  
714 on the kind of activated action. So, different parts of the same object may become  
715 affordances for different actions: for example a knife's blade can be a good affor-

716 dance for the action of cutting whereas its handle can be a good affordance for the  
717 action of grasping. The results are consistent with previous evidence showing that,  
718 depending on the situation, different object characteristics are activated (Barsalou,  
719 1982). Borghi and Barsalou (2001) showed with a feature generation task that, when  
720 participants imagine seeing a telephone, they produce mainly visual properties (e.g.,  
721 grey), when they imagine throwing it mainly tactile properties (e.g., smooth), and  
722 when they imagine hearing it, they produce mainly auditory properties (e.g., rings)  
723 (see also Klatzky, Pellegrino, McCloskey, & Doherty, 1989; Klatzky, Pellegrino,  
724 McCloskey, & Leberman, 1993; Pecher et al., 2003).

725 Experiments 4 and 5 were devised in order to prevent a possible objection. In fact,  
726 the results of Experiments 1–3 demonstrate that conceptual organization is variable  
727 and that action is a powerful mechanism for preserving object information (for con-  
728 vergent neuropsychological evidence see Magniè, Ferreira, Giuliano, & Poncet,  
729 1996), but not necessarily that concepts are embodied. In fact, they could be ex-  
730 plained by a semantic network account stating that, for example, the semantic asso-  
731 ciation between ‘cut’ and ‘blade’ is stronger than the semantic association between  
732 ‘cut’ and ‘handle’. The aim of Experiments 4 and 5 was to show with both a part ver-  
733 ification and a sensibility-rating task that this was not the case. The results clearly  
734 indicate that the effects found depend on objects’ parts affording actions, i.e., on  
735 the specific match between object properties and action, and that the results cannot  
736 be explained by an account based on semantic associations. For example, the petals  
737 and the corolla of a flower are not semantically associated to the action of stripping,  
738 but the perceptual properties of petals, their length and consistency, afford stripping  
739 much more than the perceptual properties of the corolla. Overall, the results suggest  
740 that objects are represented through symbols that are perceptual, and not arbitrary.

741 The finding that objects are conceived as patterns of potential actions is predicted  
742 by embodied and situated theories of concepts. Consider how an embodied theory of  
743 concepts can explain the results: a sentence, such as for example ‘Imagine building a  
744 car’ in Experiment 1 or ‘The woman shares the orange’ in Experiments 3–5, guides a  
745 certain simulation. This simulation leads to a selective activation of parts of the per-  
746 ceptual symbol, the car or the orange, whose perceptual characteristics are compat-  
747 ible with the action described in the sentence. Thus in Experiment 1 participants  
748 produce different parts depending on the simulation, and in Experiments 3–5 afford-  
749 ing parts are accessed earlier, and evaluated as making more sense within the sen-  
750 tence, than non-affording parts. In Experiment 2 it is not the sentence that guides  
751 the simulation, but the object name. Simulating a car leads participants primarily  
752 to access parts of the car that are relevant for canonical actions with it. This expla-  
753 nation is economical, natural and simple.

754 Even though the results are more easily predicted by an embodied account, in  
755 principle they could be also accounted for through amodal views of knowledge rep-  
756 resentation that allow for interactions between the concept core and a sort of percep-  
757 tual-motor memory. Successful amodal views postulate the existence of two levels in  
758 knowledge representation: a purely symbolic layer and a procedural layer that, oper-  
759 ating on the symbols, “instructs” the symbolic layer on how to operate in the world.  
760 Let us consider the way in which an amodal account could interpret the results of the

761 different experiments. The proponents of the amodal view might argue that the re-  
762 sults of Experiments 1 and 2, obtained through a part-generation task, reflect the  
763 association degree between a given perspective sentence and the produced parts. This  
764 explanation is weakened if one considers the fact that the experiments provide evi-  
765 dence of both canonical and situational effects, and not just of situational effects.  
766 However, an amodal account could also explain canonical effects: for example, by  
767 arguing that the symbols representing a car may have a stronger connection to sym-  
768 bols representing the steering wheel, the brake and the seats, than to symbols repre-  
769 senting the roof and the antenna. Now consider Experiment 3. The results could be  
770 due to the higher semantic relatedness between a sentence and the object's affording  
771 parts than between a sentence and the object's non-affording parts. However, the re-  
772 sults of Experiments 4 and 5, which do not depend on semantic relatedness, rule out  
773 this interpretation. In this case too, however, an amodal account could postulate the  
774 existence of some procedures for using the description to guide comprehension, and,  
775 eventually, action (e.g., when sharing an orange, focus on its slices; when eating it,  
776 focus on its pulp).

777 Thus, an amodal account could explain the results found, even though it would be  
778 difficult to predict them from an amodal point of view. Amodal accounts are very  
779 powerful, and in principle they can explain everything. However, the results found  
780 are more naturally and easily predicted by an embodied theory of knowledge, and  
781 an explanation based on an amodal account would have some shortcomings. The  
782 first shortcoming is that of symbol grounding: how do amodal accounts deal with  
783 the relationships between symbols and perception and action experience (Harnad,  
784 1990)? This leads to the second shortcoming: they can explain the results of the  
785 experiments post hoc, but there is no principled way in which they could predict  
786 them. The third shortcoming is that, in providing an explanation, they need to pos-  
787 tulate an enormous set of symbols, procedures, inter-connections between symbols.  
788 For example, they should postulate that the action of ripping a flower activates cer-  
789 tain parts, such as petals, stems and others, whereas the action of offering it activates  
790 different parts. However, in order to explain the flexibility of human knowledge, the  
791 number of symbols, links, and procedures, may become increasingly wide and create  
792 a problem of combinatorial explosion (for a more detailed discussion of this point  
793 see Borghi, Glenberg, & Kaschak, submitted for publication). So, the results suggest  
794 that concepts are represented as pattern of potential actions, and that a currently  
795 activated action increases the psychological salience of affording parts. Even though  
796 a propositional account of concepts that allow for interaction with motor memory  
797 could also account for these results, an explanation of the results based on a sen-  
798 sory-motor account of conceptualization seems more parsimonious, elegant and  
799 plausible.

800 A further point is worthy of discussion. Consider the fact that parts are generally  
801 considered as perceptual rather than functional features. The results also show that  
802 perceptual features, like parts, are differently activated depending on their power in  
803 affording actions (Tucker & Ellis, 1998). This argues for a strong interaction between  
804 perception, action (Bekkering & Neggers, 2002; Jeannerod et al., 1995; Knoblich &  
805 Flach, 2001) and conceptualization. Recent evidence in this direction has been pro-

806 vided by Glenberg and Kaschak (2002), who show that, when a sentence implied an  
807 action in a direction, participants had difficulties making a sensibility judgement  
808 requiring them to press a button moving in the opposite direction. In the same vein,  
809 Borghi et al. (submitted for publication) recently found a congruency effect between  
810 the location of a part noun, upper or lower (e.g., cork vs. bottom of a bottle), and the  
811 upper or lower location of a key to press in performing a part verification task. In the  
812 same line, Carlson (2000) has demonstrated the importance of functional informa-  
813 tion for spatial relations as ‘above’, as function significantly influences the selection  
814 of reference frames. Probably for adaptive reasons, the way we store and retain  
815 information on objects and on object parts in memory is deeply influenced by the  
816 potential actions we can perform with them (Wilson, 2002).

817 In addition, the results found imply that objects are represented componentially  
818 rather than holistically. Most interestingly, they suggest that, at least for the consid-  
819 ered items, object compositionality is grounded in action: in fact, object parts are  
820 separately activated as they may afford different actions.

821 A last point is worthy of discussion. In the last three experiments contradictory  
822 results are found with respect to the role affordances play for artifacts and natural  
823 kind concepts. In Experiment 5, which consisted in a slow rating task, the difference  
824 between concept kinds was not significant. In Experiments 3 artifacts’ non-affording  
825 parts were processed slower than artifacts’ affording parts and than natural kinds’  
826 parts, in Experiment 4 artifacts’ affording parts elicited less errors than artifacts’  
827 non-affording parts and than natural kinds parts. Evidence convergent with the  
828 advantage of artifacts’ affording parts is provided by studies showing that artifacts  
829 mainly elicit functional and action features. This evidence could also be accounted  
830 for by a domain-specific view of knowledge organization, according to which evolu-  
831 tionary pressures have resulted in specialized neural circuits dedicated to processing  
832 different categories. As argued by Mahon and Caramazza (in press), the plausible  
833 candidates for this are the categories that are relevant for our evolutionary history  
834 such as animals, plants, con-specifics, tools.

835 However, the results suggest that the difference between artifacts and natural  
836 kinds could be simply a matter of grade, due to the fact that artifacts are more often  
837 acted with in the same way, while natural kinds are not (Parisi, personal communi-  
838 cation). For example, we generally use chairs for sitting, while we generally interact  
839 with cats in many different ways—petting them, feeding them, playing with them—so  
840 that several parts may become salient. Thus, the results open the interesting possibil-  
841 ity that all concepts, and not only artifacts, are conceived as possible action patterns.

842 Another possibility is partially compatible with the results found. It is possible  
843 that the absence of a clear difference between artifacts and natural kinds is due to  
844 the fact that both the artifacts and the natural kind concepts used were manipulable  
845 and are generally acted with. In this line, recent papers suggest that the difference  
846 between artifacts and natural kinds should be reformulated in terms of the difference  
847 between manipulable artifacts and natural kinds such as watches and oranges, and  
848 non-manipulable artifacts and natural kinds such as statues and stars (Gerlach,  
849 Law, & Paulson, 2002).

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## 865 Appendix A

### 866 *A.1. Experiments 1 and 2—materials*

- 867 1. Bicycle
- 868 2. Washing machine
- 869 3. Car
- 870 4. Piano
- 871 5. Motorbike
- 872 6. Mixer
- 873 7. Hi-fi
- 874

### 875 *A.2. Experiment 3—materials*

- 876 1. The child divided the orange/tasted the orange—slice/pulp.
- 877 2. The woman ate the watermelon/threw the watermelon away—seed/skin.
- 878 3. The man cut the grapes off/savored the grapes (uva)—stalk/grape (\* in Italian it's  
879 a different word: acino).
- 880 4. The girl pet the cat/bothered the cat—head/tail.
- 881 5. The girl fed the bird/picked up the bird—beak/wing.
- 882 6. The girl rode the pony/fed the pony—back/muzzle.
- 883 7. The man sawed the tree/paused under the tree—trunk/leafy branch.
- 884 8. The boy cut the flower/gave the flower as a present—stem/corolla.
- 885 9. The boy picked up the rose/smelled the rose—thorn/petal.
- 886 10. The man chewed the fish/caught the fish—bone/mouth (of the fish).



- 887 11. The woman cleaned the artichoke/enjoyed/savored the artichoke—leaves/hearth.  
 888 12. The man pruned the olive tree/planted \* (cut off) the olive tree—branch/root.  
 889 13. The man grasped the knife/cut with the knife—handle/blade.  
 890 14. The boy untied the shirt/folded the shirt—button/arm.  
 891 15. The girl read the book/found the book—page/cover.  
 892 16. The woman opened the bottle/raised the bottle—cork/bottom.  
 893 17. The woman put the skirt on/ironed the skirt—zip/fold.  
 894 18. The child leaned against the chair/turned the chair over—back/legs.  
 895 19. The girl closed the door/slammed the door—handle/shutter.  
 896 20. The man loaded the car/drove the car—trunk/steering wheel.  
 897 21. The boy lay down on the bed/sat on the bed—mattress/headboard.  
 898 22. The girl controlled the watch/took the watch off—(watch) strap/(watch) hand (\*  
 899 in Italian both words are specific for watches: cinturino, lancetta).  
 900 23. The man played the piano/transported the piano—key/tail.  
 901 24. The boy set the table/lifted the table—shelf (of the table)—feet.  
 902

903 *A.3. Experiments 4 and 5—materials*

- 904 1. The woman shares/distributes the orange—slice—pulp.  
 905 2. The boy takes the cat—stomach—eye.  
 906 3. The girl throws the watermelon away—skin—seed.  
 907 4. The boy devours the artichoke—hearth—leaves.  
 908 5. The girl rips/tears the flower—petal—corolla.  
 909 6. The boy picks up the bird—legs—beak.  
 910 7. The girl hugs/embraces the tree—branch—leaves.  
 911 8. The man caught the fish—mouth—bone.  
 912 9. The girl keeps the butterfly—wings—head.  
 913 10. The woman mounts the bear—back—muzzle.  
 914 11. The boy feeds the dog—tongue—tail.  
 915 12. The girl puts the watch down—watch strap—watch hand.  
 916 13. The boy extracts the book—cover—page.  
 917 14. The man gets off the motorbike—pedal—light.  
 918 15. The woman smoothes the shirt—arm—knob.  
 919 16. The girl puts the bottle down—neck—cork.  
 920 17. The woman dyes the jacket—pocket—zip.  
 921 18. The man enters the car—seat—trunk.  
 922 19. The man paints the door—hinge—lock.  
 923 20. The boy lifts the wardrobe—legs—shutter.  
 924 21. The woman raises the glasses—legs (\*in Italian it is a word specific for glasses)—  
 925 lens.  
 926 22. The man cleans the computer—screen—key.  
 927

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